# **ADAM-6022**

## **Ethernet-based Dual-loop PID Controller**



ADAM-6022

**C€ FCC** 

# **Specifications**

#### General

LAN

Power ConsumptionLoop Number4 W @ 24 Vdc2 (3 Al, 1 AO, 1

2 (3 AI, 1 AO, 1 DI, 1 DO for each control loop)

10/100Base-T

## **Analog Input**

 Accuracy ±0.1 % or better
 Bandwidth 13.1 Hz @ 50 Hz 15.72 Hz @ 60 Hz

Channels 6 differential
CMR @ 50/60 Hz 92 dB min.

Resolution 16 bits
Input Impedance 20 M

• Input Range  $0 \sim 10 \text{ V}_{DC}$ ,  $0 \sim 20 \text{ mA}$ ,

## **Analog Output**

• Channels 1

Accuracy 0.05% of FSR

- Channels 2

Drift ±50 ppm/° C
 Drive Voltage 15 V<sub>DC</sub> (current output)

• Output Range  $0 \sim 10 \text{ V}_{DC}, 4 \sim 20 \text{ mA}, 0 \sim 20 \text{ mA}$ 

Resolution 12 bits

## Digital Inputs

Channels

Open Collector to 30 V 100 mA max. load

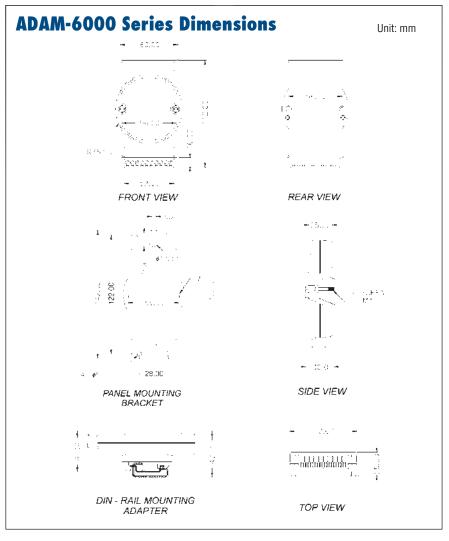
300 mW

Isolation Voltage 2,000 V<sub>DC</sub>

• Fault and Overvoltage Withstands overvoltage

overvoltage

Power Reversal Protection
 Protection up to +/-35 V<sub>DC</sub>



#### **Digital Outputs**

Channels

Open Collector to 30 V 100 mA max. load

**Fault and Overvoltage** Withstands overvoltage up to +/-35 V<sub>DC</sub>

### **Environment**

 Humidity (Operating)
 20 ~ 95% RH, (non-cond)

• **Humidity (Storage)** 0 ~ 95% RH, (non-cond.)

• Operating Temperature  $-10 \sim 50^{\circ}$  C

• Storage Temperature  $-20 \sim 80^{\circ} \text{ C}$ 

# **Ordering Information**

- ADAM-6022

Dual-loop PID Controller